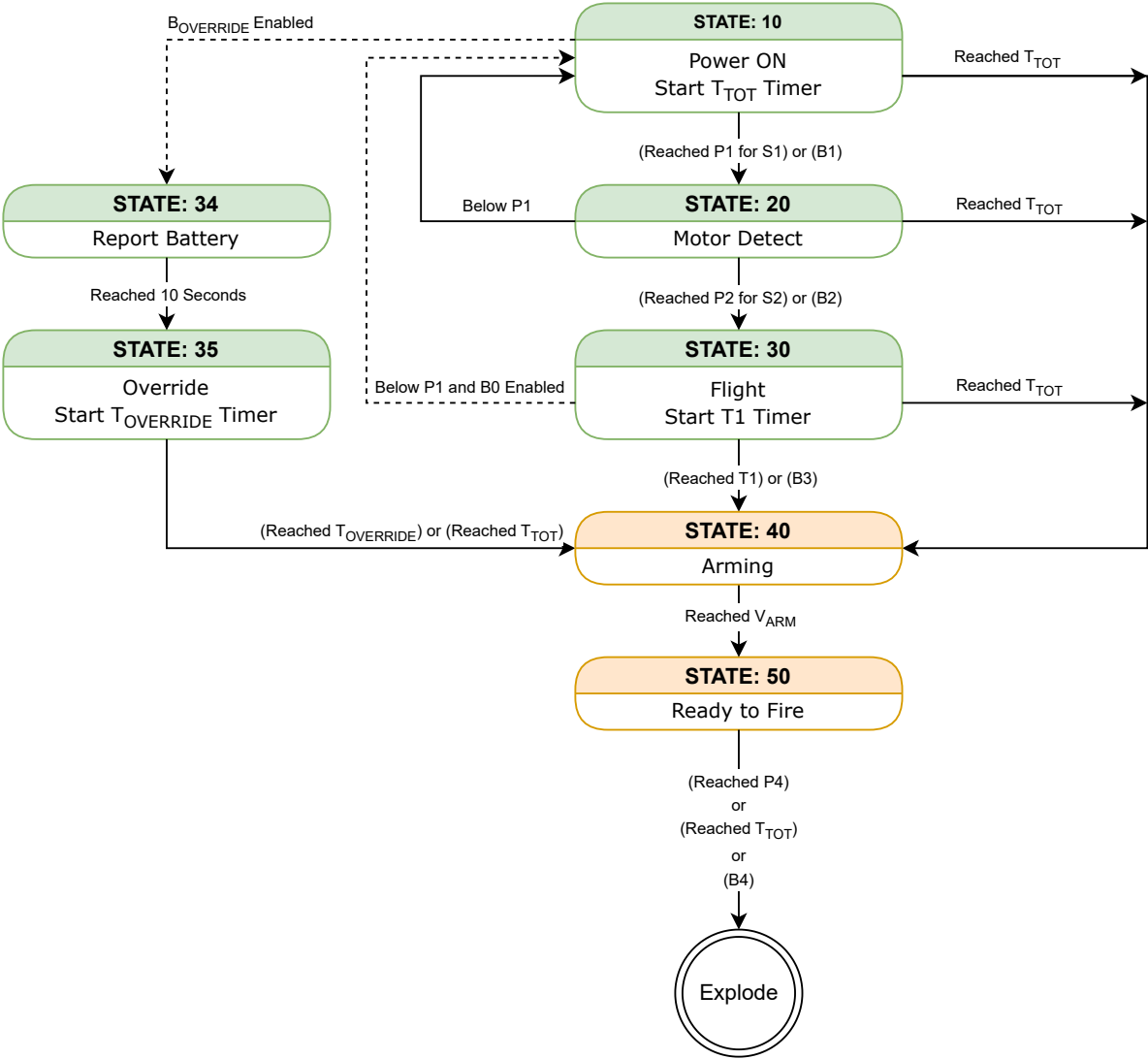




Parameter	Unit	Description	Default	Min:Max
T _{TOT}	minutes	Self Destruct Timer	30	10:900
P1	level	Motor Spin Detection Sensitivity	45	10:200
S1	seconds	Motor Spin Detection Sample Interval	3	1:30
P2	level	Flight Detection Sensitivity	150	50:500
S2	seconds	Flight Detection Sample Interval	1	1:30
T1	seconds	Delay from Flight Detect to Arming	30	0:600
P4	level	Impact Level	4000	2000:7900
P5	milliseconds	Impact Detection Window	10	2:40
B0	bool	Flight Stop Detection Permission	1	0:1
B1	bool	Bypass Motor Detection	0	0:1
B2	bool	Bypass Flight Detection	0	0:1
B3	bool	Ignore T1 Delay	0	0:1
B4	bool	Ignore Impact Detection	0	0:1
B5	bool	State 35, 40, 50 LED's OFF	0	0:1
V _{ARM}	1/10 volts	Arming Voltage	60	40:140
B _{VERRIDE}	bool	Enable Immediate Jump to Arm State	0	0:1
T _{VERRIDE}	seconds	Time from Power On to Arm State	5	0:65535

Status LED's		
State	Green LED	Red LED
10	2 Blinks then Pause	See Note 1
20	Medium Blink	OFF
30	Fast Blink	OFF
34	3 Blinks then Pause	See Note 1
35	Solid	OFF
40	Slow Blink	Slow Blink
50	OFF	Fast Blink
Explode	OFF	OFF

Note 1: Red LED is OFF, unless the battery is low, then red LED pattern matches the green